



전력전자학술대회 - MathWorks 산업기술세션

# MathWorks Korea 온라인 설문조사

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추첨을 통해 **커피 기프트콘**을 보내드립니다!



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e8mXh8zaF8](https://forms.office.com/r/e8mXh8zaF8)

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# Hardware-in-the-Loop Testing of Battery Management System with Speedgoat Real-time Target Machine

**speedgoat**  
real-time simulation and testing

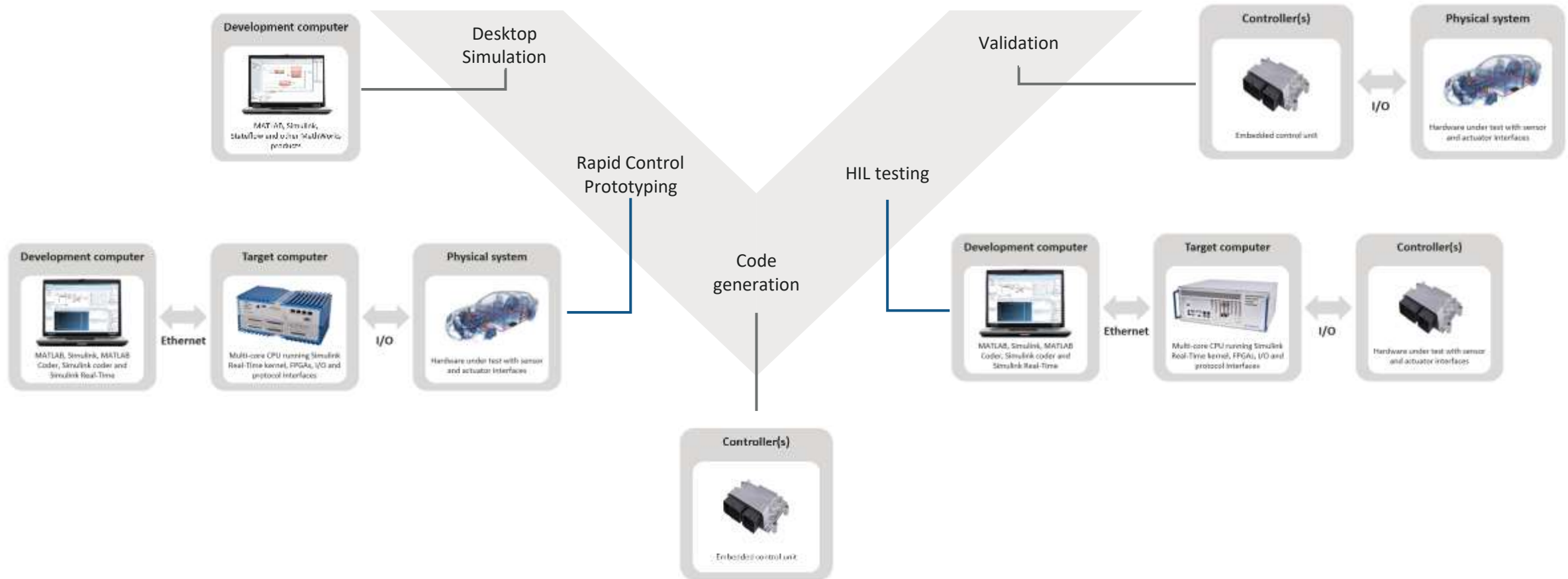
**Innox**  
(주) 이노엑스

# About Speedgoat

- MathWorks associate company, incorporated in 2006 by MathWorks employees in Switzerland, with subsidiaries in the USA, Germany and worldwide Distributors
- At MathWorks and Speedgoat people involved in developing real-time simulation and testing solutions continuously grew (currently 120)
- MathWorks and Speedgoat are collaborating at all levels
- Provider of real-time target computers, expressly designed for use with Simulink



# Real-Time Testing Configurations







## MathWorks: Simulink Real-Time (SLRT)

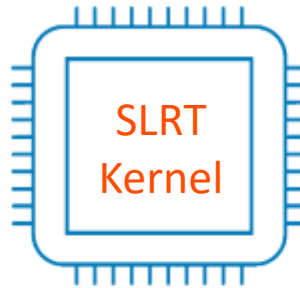


Two companies  
form a complete Solution



## Speedgoat Real-time Target Machines

- RT - instrumentation
- Code Gen (C/VHDL)
- Toolboxes / Blocksets
- Simscape
- Simulink Test



- I/O-/protocol support
- FPGA-based solutions
- Speedgoat driver library
- Complete HIL-Rigs

# Broad Range of Applications and Industries

## Wherever Real-Time Electronic Controls is Applied

Industries	Applications
<b>Aerospace/Space and Defense</b>	Civil and military aircrafts, military vehicles, unmanned crafts, missiles, satellites, ships, submarines, space crafts and components, ...
<b>Automotive</b>	Driverless and non driverless passenger and racing cars, trucks, off-highway vehicles, motorbikes, construction and agricultural machinery. Electric and combustion engines, inductive charging, ...
<b>Energy</b>	Supergrids and microgrids, fusion reactors, linear colliders, solar inverters, wind turbines, alternative-fuel engines, ...
<b>Automation and controls</b>	Motion control, power and energy systems, robotics, industrial control, sensors and actuator technology, building control, and process machinery
<b>Medical devices</b>	Medical devices such as eye laser surgery equipment, prosthesis and exoskeletons, hearing devices and implants, bio-medical process machinery, ...
<b>Consumer Electronics</b>	Smartphones and laptops including camera, audio, thermal, and battery technologies, augmented and virtual reality technologies, storage devices, printers, ...
<b>Academia</b>	Verification and test of theoretical concepts, teaching of students, development of new technologies for commercial applications

# User Stories and and Customers

Find all the user stories here ->

[Speedgoat User Stories](#)

[Simulink Real-Time User Stories](#)

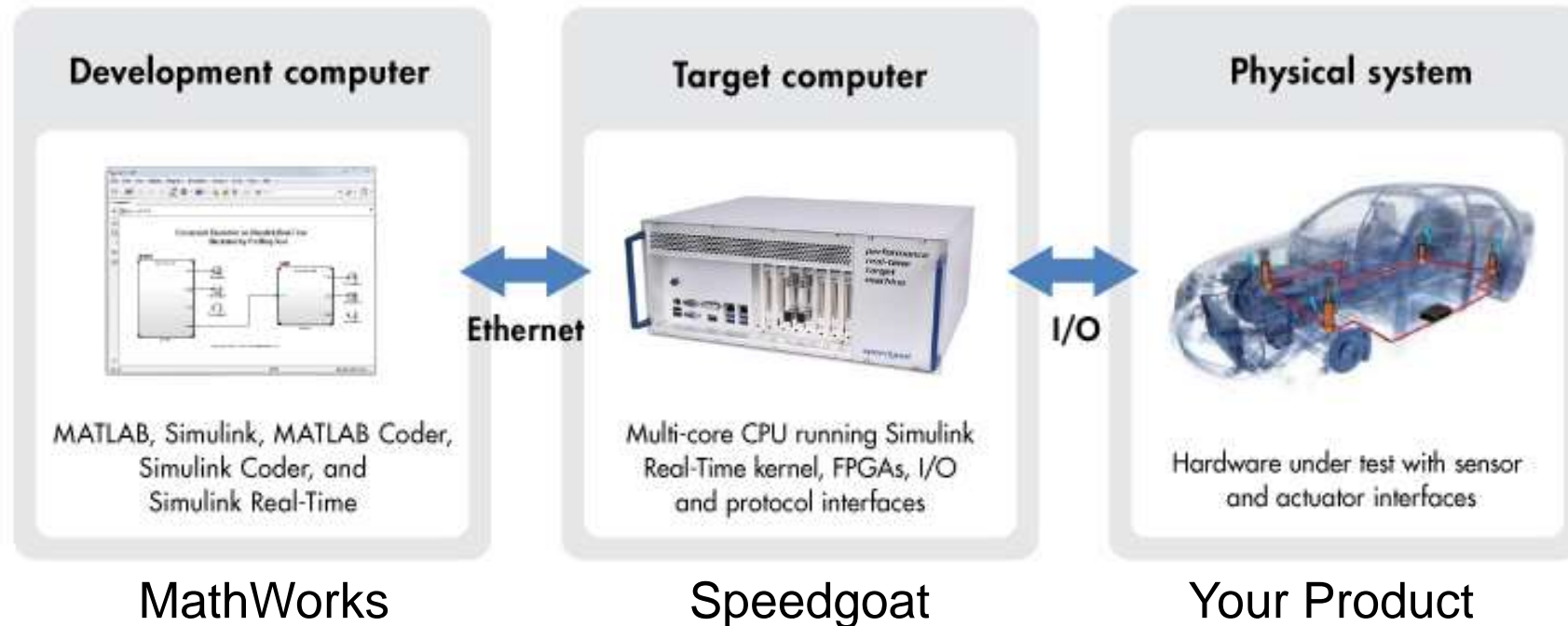


# A Complete Solution for Desktop and Real-Time Simulation and Testing using Simulink





# Real-time simulation and testing from within Simulink, with real-time hardware tailored to your needs

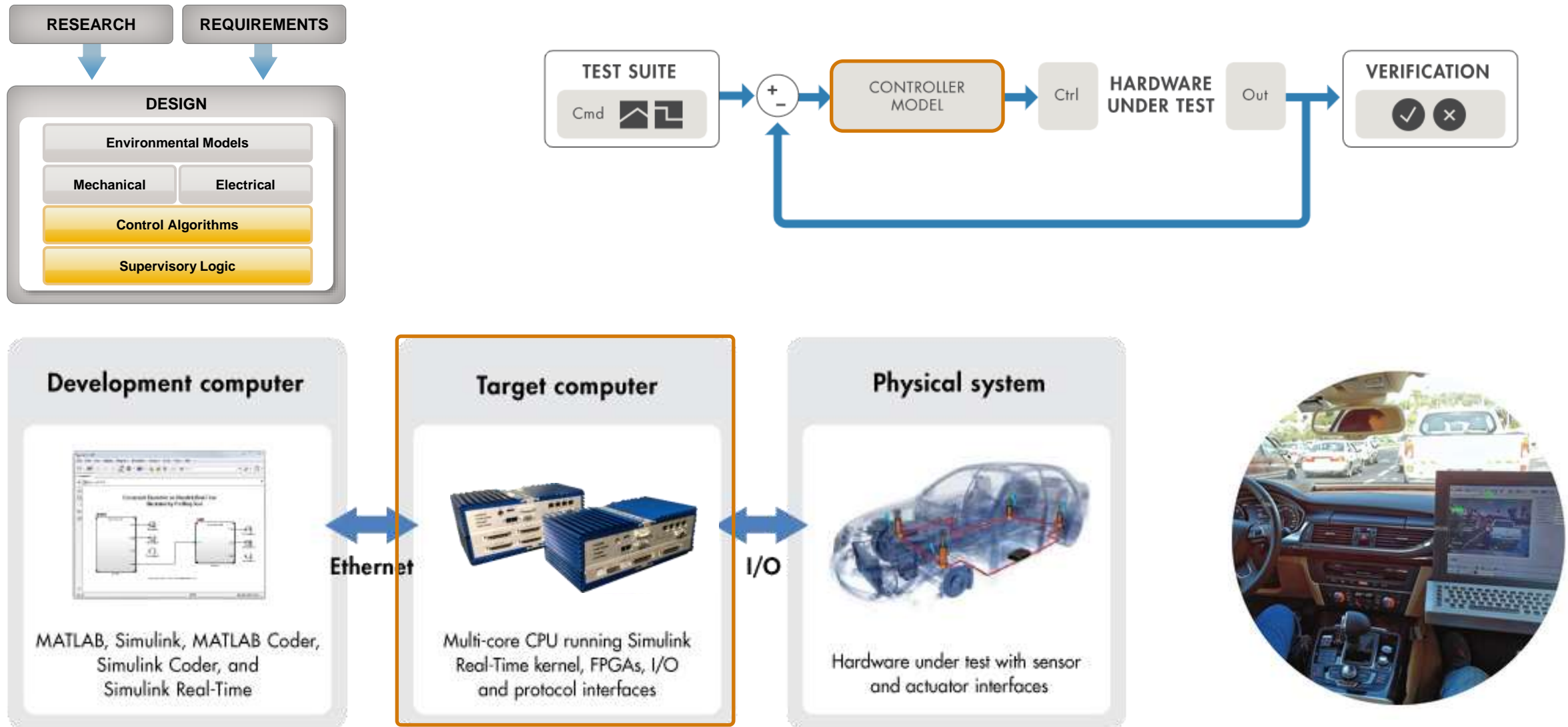


**"...plug-and-play  
real-time platform for  
Simulink."**

*Joaquin Reyes, Controls  
Engineer, Proterra Electric  
Buses, USA*

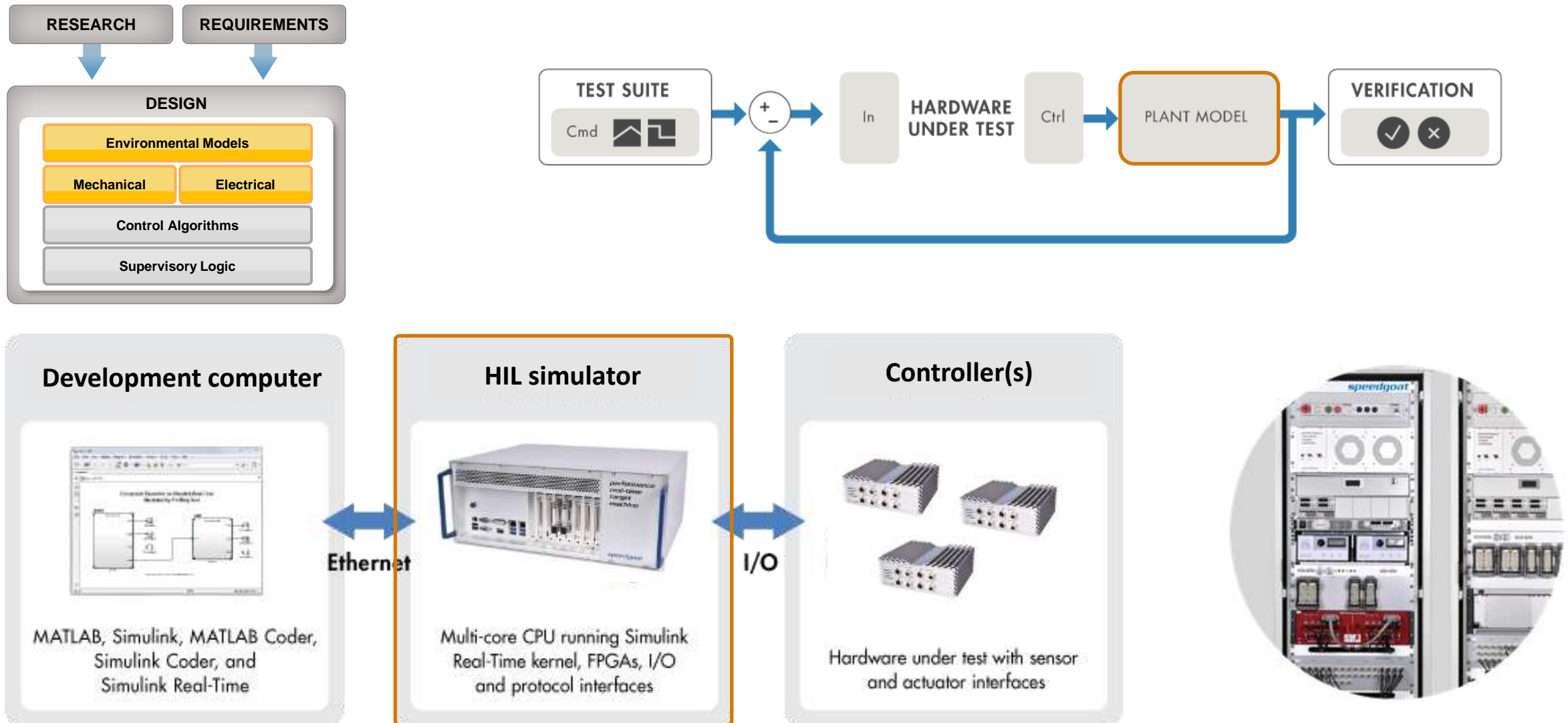


# Rapid Control Prototyping



Real-time controls application auto-generated from Simulink

# Hardware-in-the-Loop Simulation

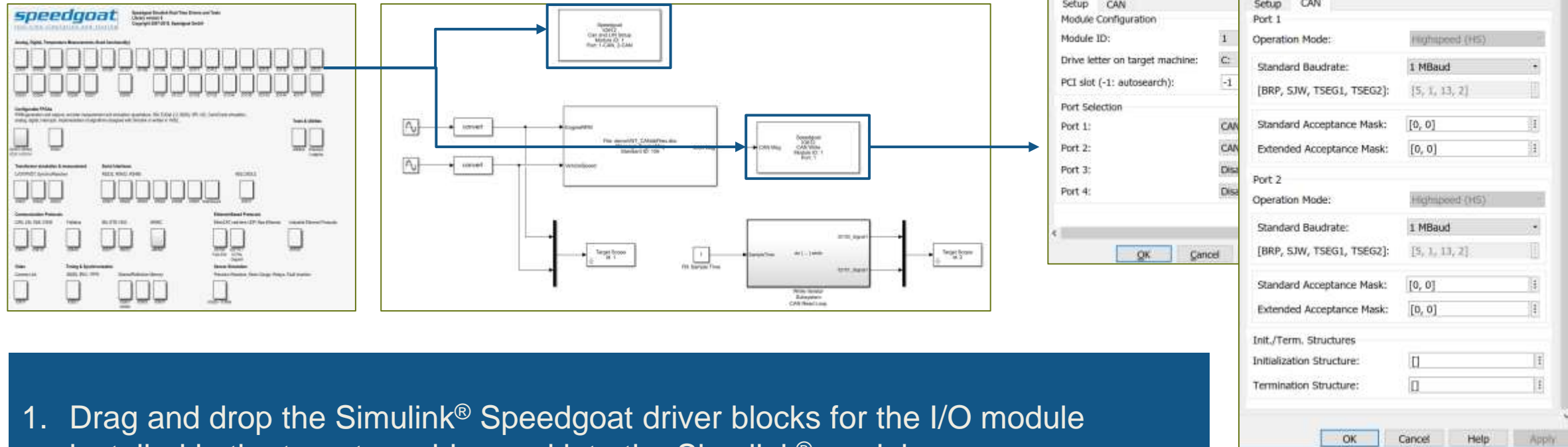


Plant simulation application autogenerated from Simulink



# From Desktop to Real-Time Simulation and Testing

## Add and Configure I/O and Protocols Blocks to a Simulink® Model



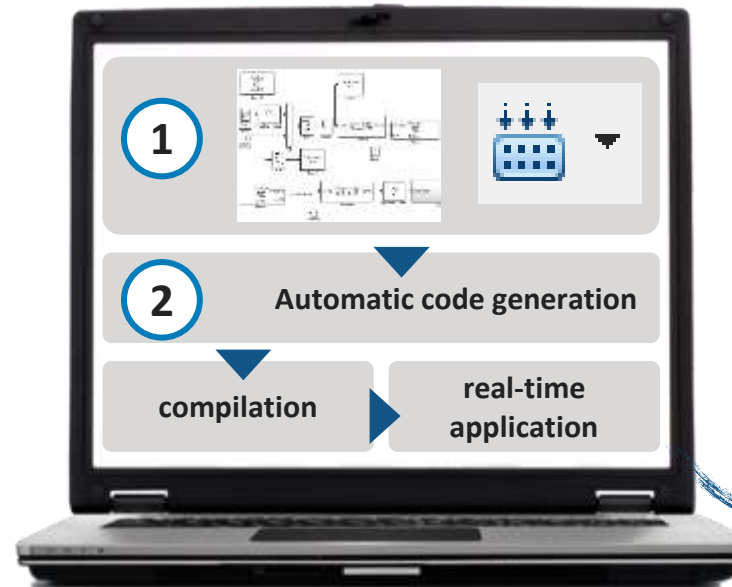
1. Drag and drop the Simulink® Speedgoat driver blocks for the I/O module installed in the target machine and into the Simulink® model
2. Connect driver blocks I/O ports to the Simulink® blocks
3. Configure the I/O and protocol settings in the dialog fields of the driver blocks



# From Desktop to Real-Time Simulation and Testing

## Automatically Create Your Real-Time Application from Simulink®

- 1 Add Simulink® Speedgoat I/O driver blocks
- 2 Automatic C and VHDL code generation and compilation
- 3 Automated target transfer, ready to run

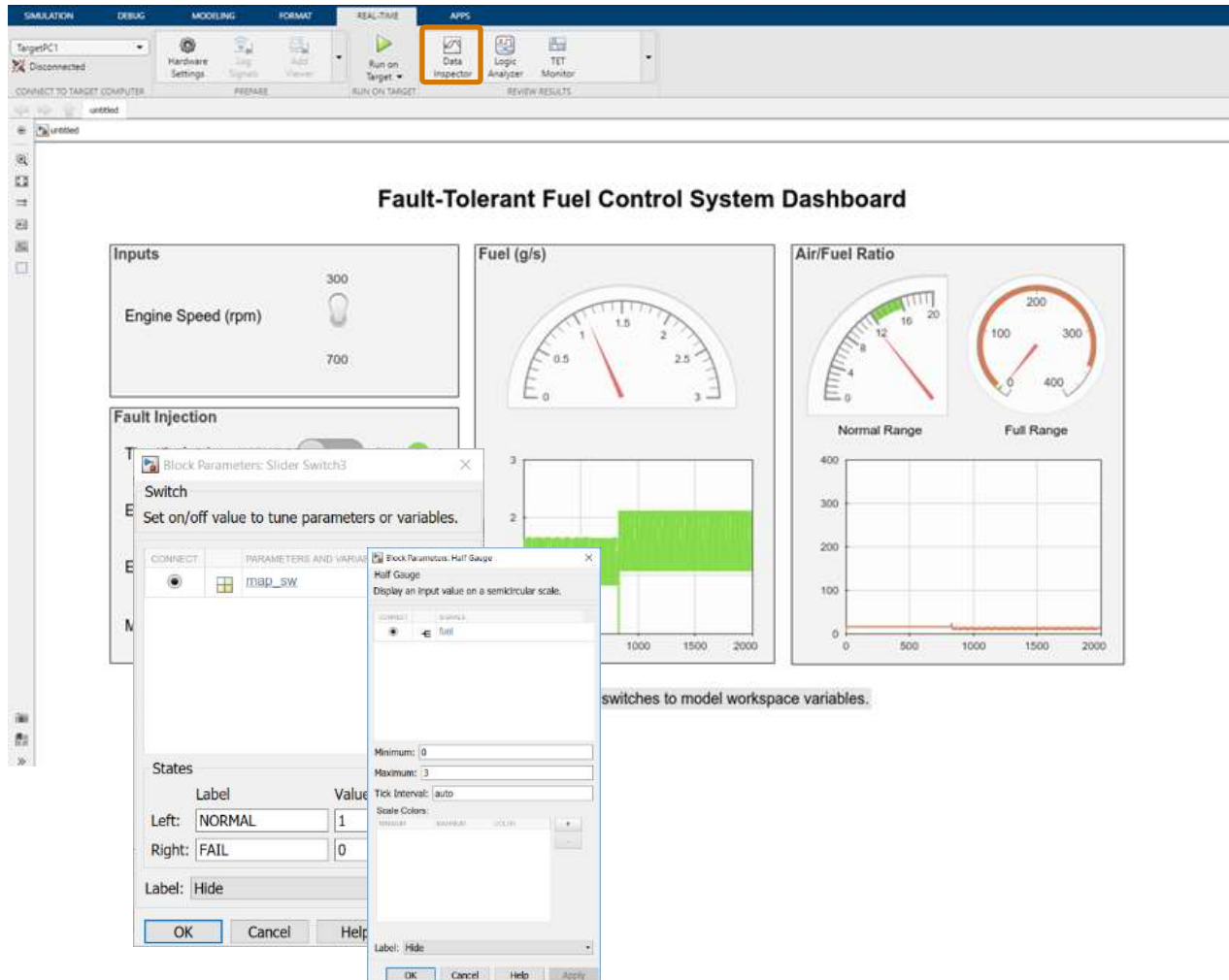


Target machine with multicore CPU, FPGAs and I/O



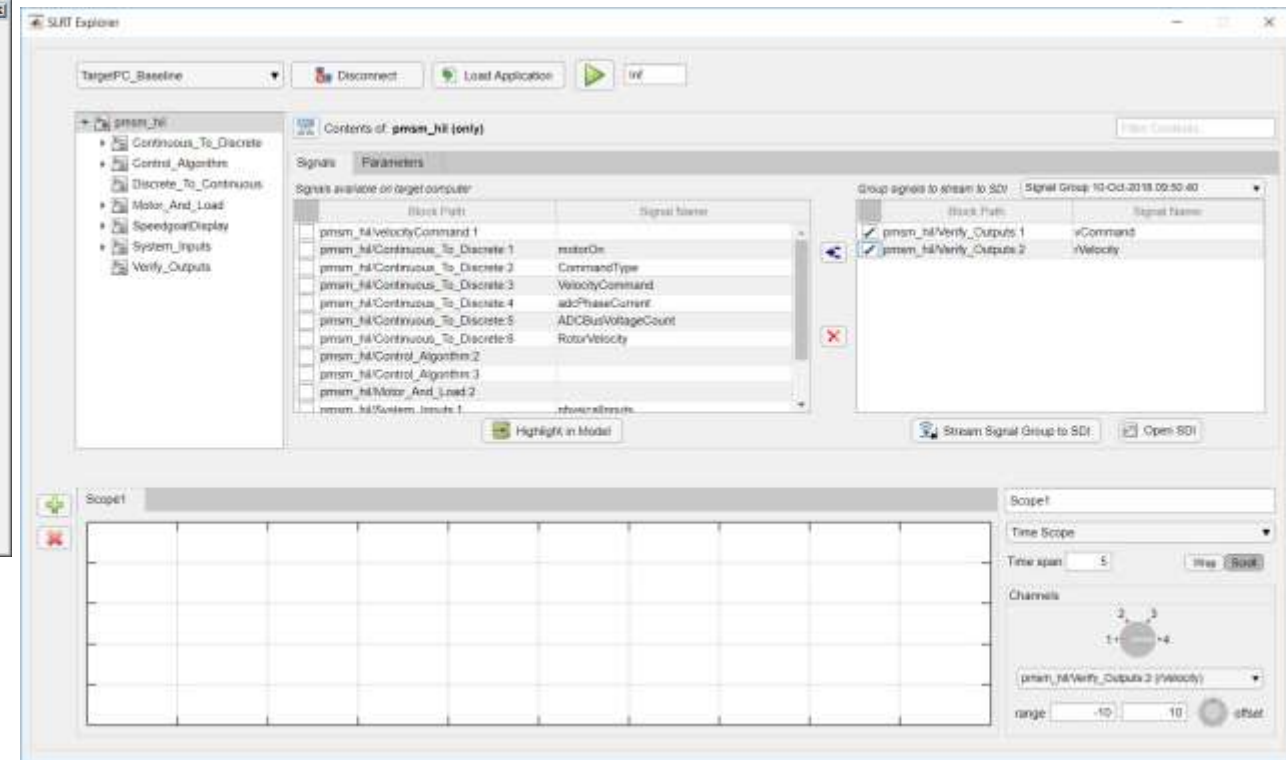
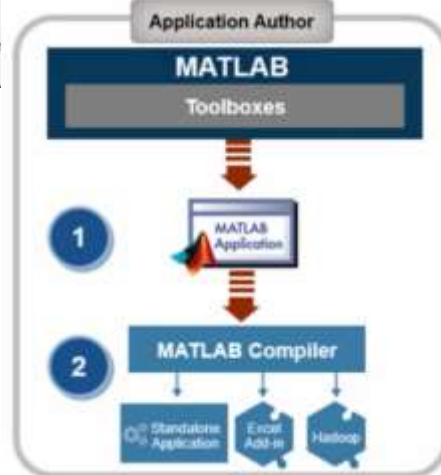
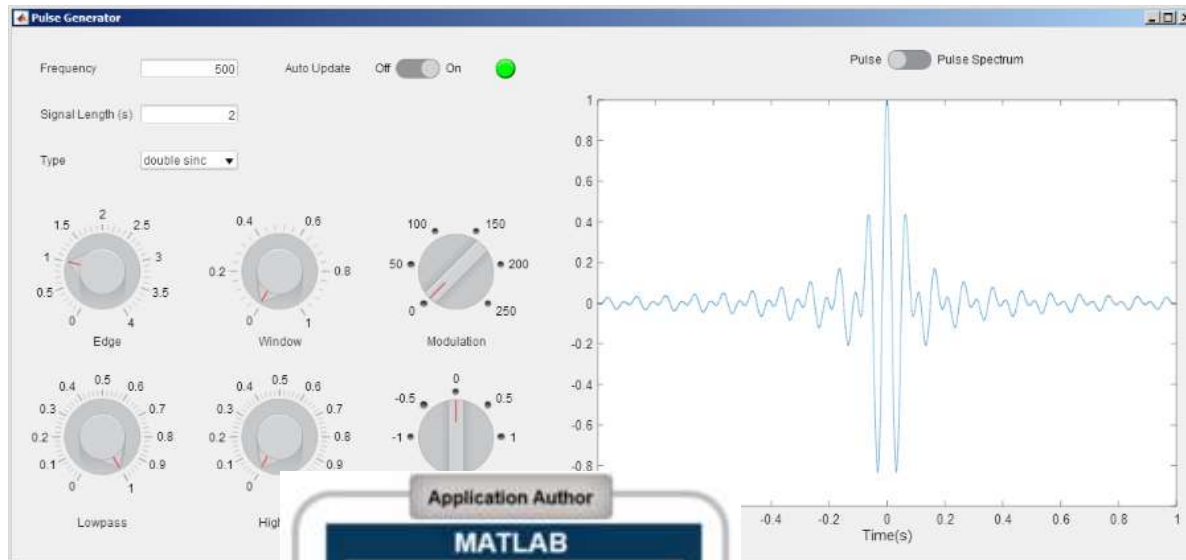
# Fast-Track from Desktop to Real-Time Simulation and Testing

## Real-time tune parameters, monitor signals and data logging



# Real-Time Simulation and Testing Instrument and Monitor Your Real-Time Application

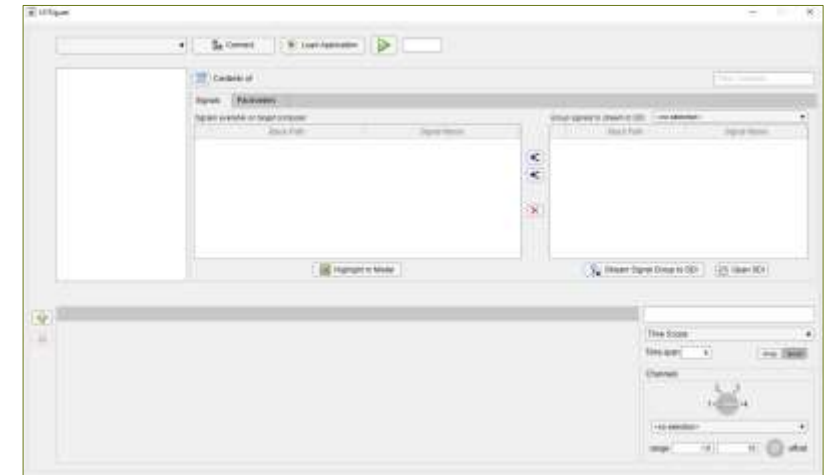
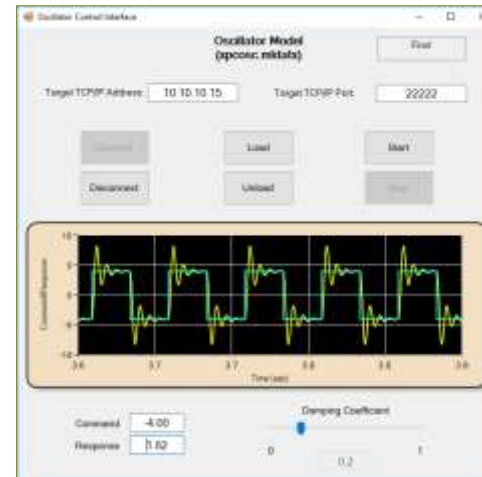
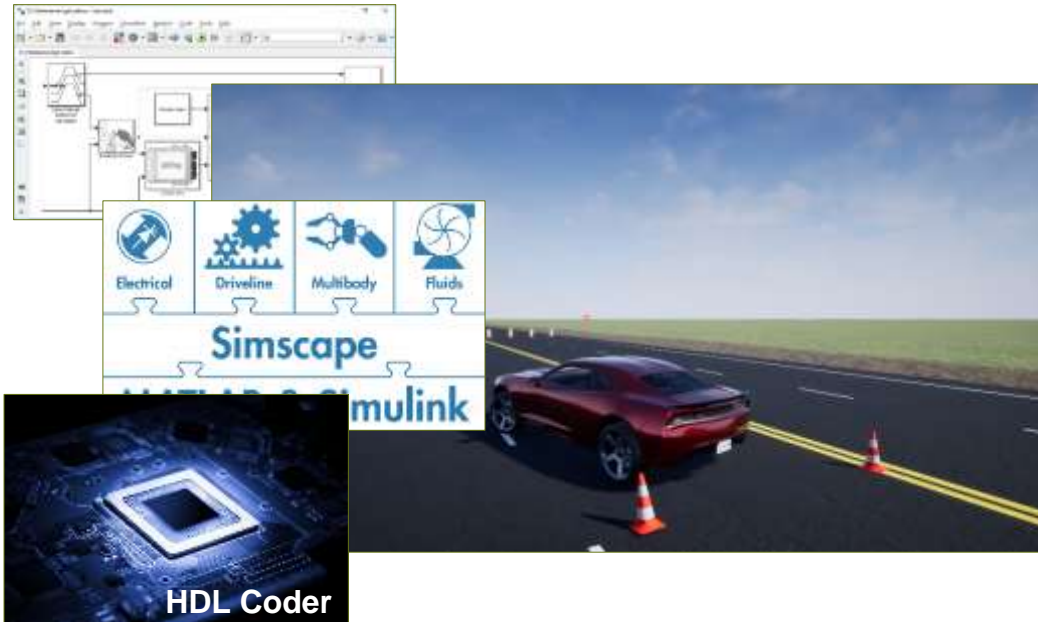
Using standalone Windows GUIs with royalty free application distribution



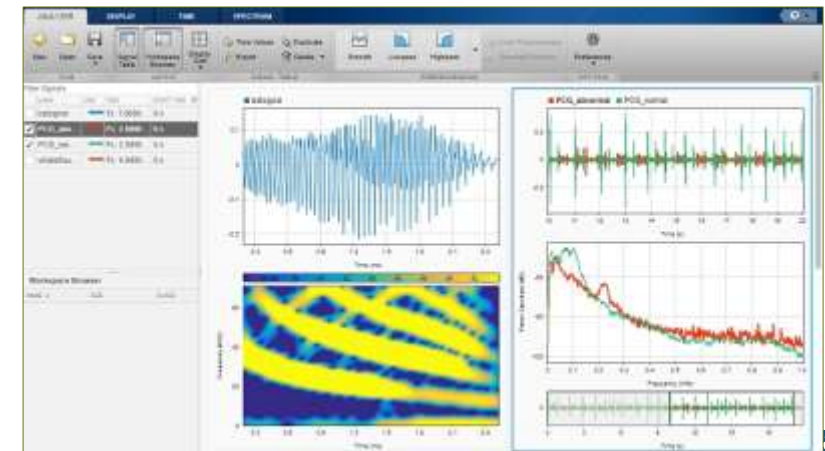
**MATLAB App Designer**  
(standalone supported with MATLAB Compiler)

# From Desktop to Real-Time Simulation and Testing

## Extendable, Integrated and Interactive



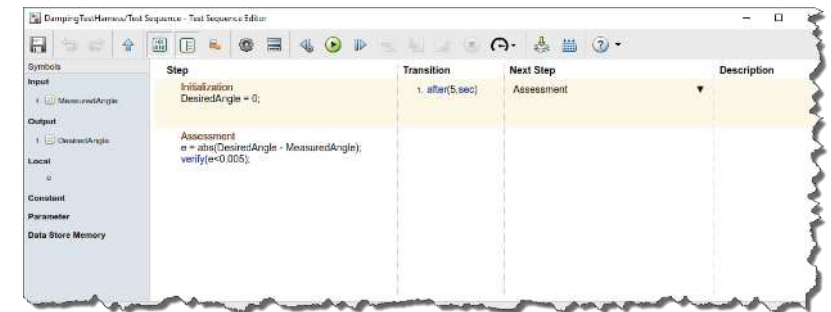
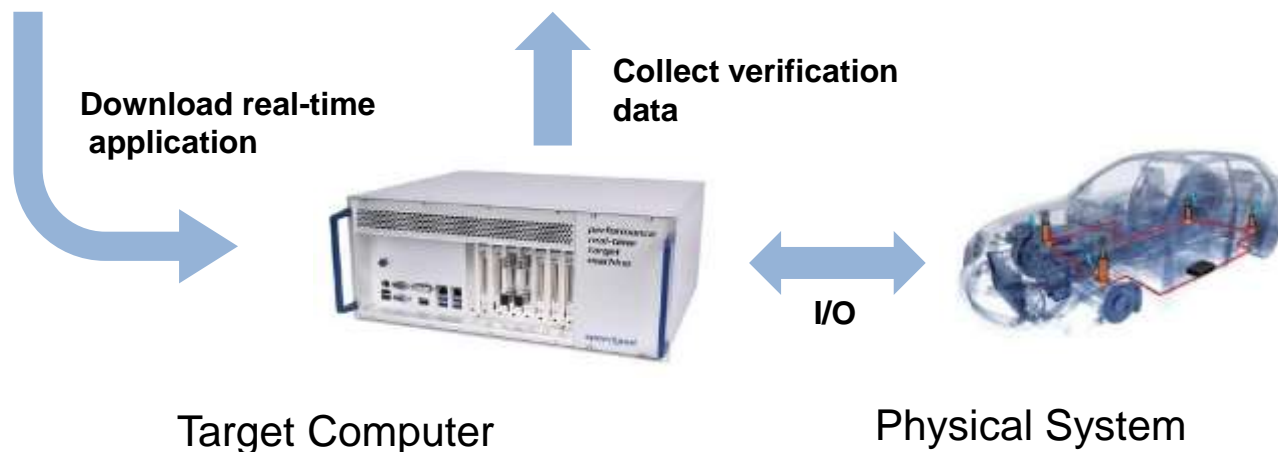
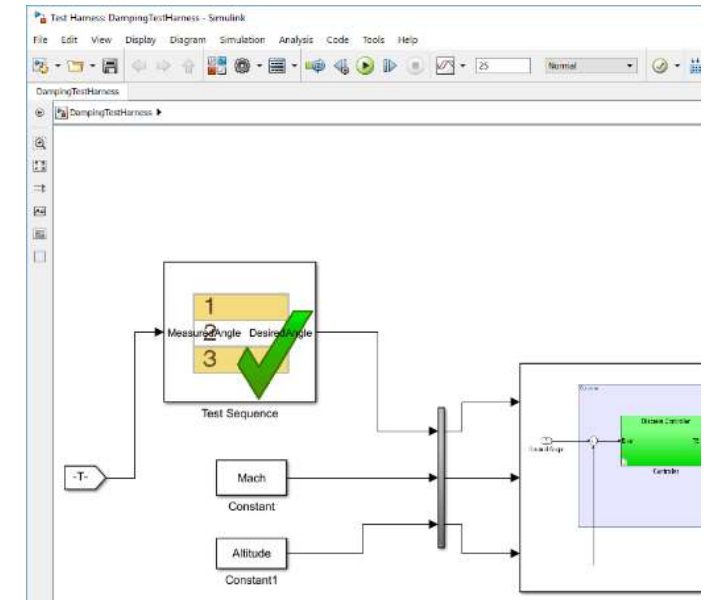
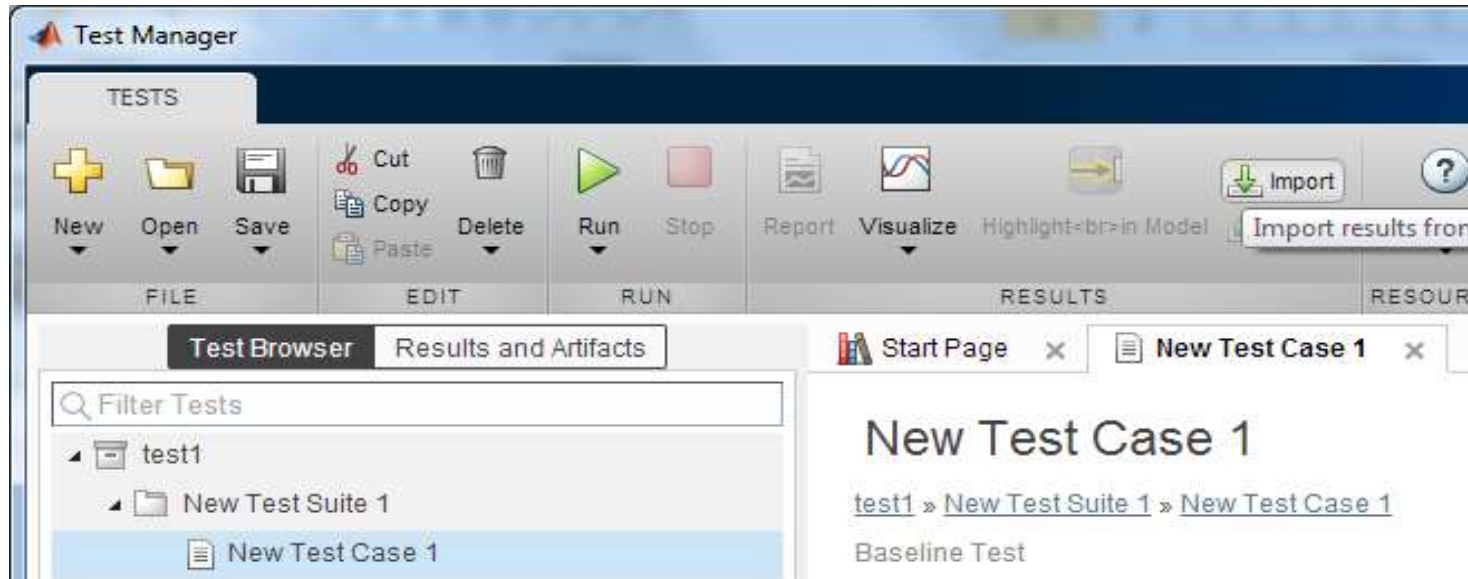
- Extensibility with other MathWorks products and third-party tools
- User interfaces for enhanced usability and standalone operation
- Data logging for offline analysis in MATLAB®





# Automated Testing with Simulink Test

## Real-Time Test Automation, ideal for Hardware-in-the-Loop



# Real-time target machines, I/O, and protocols



# Speedgoat Products and Services

## Made for Simulink, Tailored to Your Needs



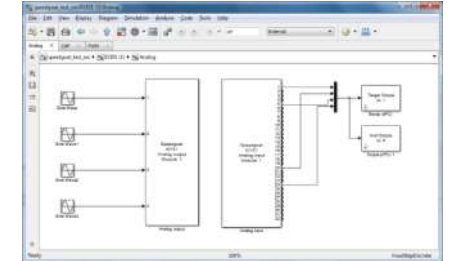
Real-time target machine



I/O modules installed in target machine



Simulink driver blocks



Simulink test models

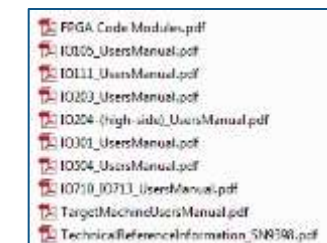


I/O cables



Terminal boards

- Real-time target machines for office, lab, and field use
- 150+ commercial off-the shelf I/O modules
- Each target machine is configured to meet your sample rate, I/O, and environmental requirements
- Simulink Real-Time is expressly and exclusively designed to work together with Speedgoat hardware
- Most current MATLAB release always supported



Documentation



Support, Training,  
Consulting, and Warranty  
Services



# Performance real-time target machine

## Built for High Performance and Scalable



- Latest Intel CPUs with up to 8 cores
- Concurrent multicore CPU and FPGA real-time application execution
- Up to 50 I/O modules installable leveraging additional expansion chassis
- Built for Hardware-in-the-Loop testing and Rapid Control Prototyping
- Ideal for both, rack installation and desk use



# Mobile real-time target machine

## High Performance with Compact Form Factor



- Ideal for mobile and in-vehicle use
- Intel Core i7 2.5 GHz dual core CPU and FPGAs
- Rugged and fanless, extended temperature support
- Stackable: Up to 14 I/O modules supported
- With or without enclosure (openframe)
- 12+ years life cycle

# Baseline real-time target machine

## Compact and rugged yet Performant



- Ideal platform for applications requiring few channels, but a diverse set of I/O
- Intel Celeron 2.0 Quad Core CPU and optional FPGAs
- Over 100 compact miniPCle, PMC, and XMC form factor modules supported
- For desk, field, and in-vehicle use
- Rugged compact design with extended temperature support
- Available with expandable enclosure and openframe



# Unit real-time target machine

## Small-scale Rapid Control Prototyping



- Intel® Atom® quad-core 1.6 GHz CPU
- For desk, field, and in-vehicle use
- Rugged compact design with extended temperature support
- Available with expandable enclosure and openframe
- Dimensions: H 60 mm x W 140 mm x D 100 mm

# I/O Connectivity and Protocols Support

**Vast range of I/O and protocols supported by over 200 I/O modules**



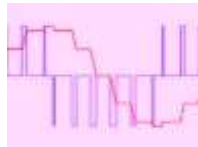
**Analog**  
A/D D/A 16-24 bit



**Digital**  
TTL, RS422, LVDS



**Communications**  
CAN, UDP, PROFINET...



**Pulstrain/FPGA**  
PWM/Cap



**Encoders**  
QAE, QAD, BiSS, SSI...



**Battery Management**  
emulation and simulation



**Temperature & Strain**  
thermal sensors & strain gauges



**Resistors**  
High Precision



**Fault Injection**  
MOSFET switch



**Audio & Speech**  
High performance analog modules



**Relays**  
SPST, SPDT, DPST



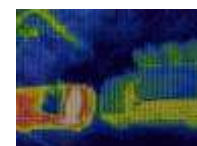
**LVDS/RVDT/  
Synchro/Resolver**  
Measure and simulate



**Vibration**  
IEPE/ICP



**Shared Memory**  
2.5 Gbps



**Video**  
Camera Link, USB



**Timing**  
GPS, IRIG, PTP



# Buses and Networks

## Automotive



- CAN, CAN FD
- LIN
- FlexRay
- XCP, SAE J1939
- SENT
- PSI5
- Automotive Ethernet w/ SOME/IP

## Aerospace



- ARINC (429, 629, 825)
- AFDX (ARINC 664 P7)
- SDLC/HDLC
- MIL STD 1553
- DShot

## Automation



- Modbus (TCP, RTU)
- EtherCAT
- PROFIBUS
- PROFINET
- POWERLINK
- Ethernet/IP
- CANOpen

## Energy



- DNP3
- IEC61850
- Modbus (TCP, RTU)

## Railway



- MVB
- WTB

## Multi-Industry



- |            |          |
|------------|----------|
| • UDP      | • PTP    |
| • TCP/IP   | • Aurora |
| • SPI, SSI |          |
| • I2C      |          |

# I/O Connectivity and Protocols Support

## Two types of FPGA I/O modules

### 1. Configurable FPGA I/O Modules

- Cost effective hardware configurations
- Selectable configuration files with support for I/O requiring fast frequency support:
  - PWM generation and capture
  - Incremental and absolute encoders
  - SPI and I2C protocol support
  - ...

For closed-loop sample rates below 20kHz

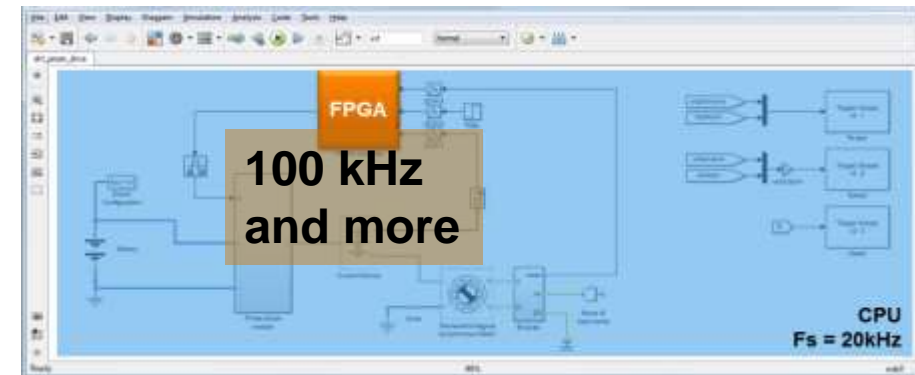
Pin on Term. Board	Code Module Channel Address	Input #	Functionality	Trans. color	Port	Pub. Modulators	Pin on Term. Board	Code Module Channel Address	Input #	Functionality	Trans. color	Port	Pub. Modulators
1	1	1	PWM - A	TTL	1	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating	35	1	0	QAD - A	TTL	4	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating
2			PWM - B	TTL			36			QAD - B	TTL		
3			PWM - Trigger	TTL			37			QAD - Chindex	TTL		
4	2	1	PWM - A	TTL	1	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating	38	2	0	QAD - A	TTL	4	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating
5			PWM - B	TTL			39			QAD - B	TTL		
6			PWM - Trigger	TTL			40			QAD - Chindex	TTL		
7	3	1	PWM - A	TTL	1	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating	41	3	0	QAD - A	TTL	4	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating
8			PWM - B	TTL			42			QAD - B	TTL		
9			Ground				43			Ground			
10	3	1	PWM - Trigger	TTL	2	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating	44	3	0	QAD - Chindex	TTL	4	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating
11			PWM - A	TTL			45			QAD - A	TTL		
12			PWM - B	TTL			46			QAD - B	TTL		
13	4	1	PWM - Trigger	TTL	2	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating	47	4	0	QAD - Chindex	TTL	4	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating
14			PWM - A	TTL			48			QAD - A	TTL		
15			PWM - B	TTL			49			QAD - B	TTL		
16	5	1	PWM - Trigger	TTL	2	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating	50	1	0	Intermitt Input	TTL	4	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating
17			PWM - A	TTL			51				TTL		
18			PWM - B	TTL			52				TTL		
19	6	1	PWM - Trigger	TTL	3	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating	53	1	1	QAE - A	TTL	7	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating
20			PWM - A	TTL			54			QAE - B	TTL		
21			PWM - B	TTL			55			QAE - Chindex	TTL		
22	7	1	PWM - Trigger	TTL	3	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating	56	2	1	QAE - A	TTL	7	pull-up 3.3 VDC, weak pull-up 5.0 VDC, pull-down, floating
23			PWM - A	TTL			57			QAE - B	TTL		
24			PWM - B	TTL			58			QAE - Chindex	TTL		

### 2. Simulink Programmable FPGA I/O Modules

- Large Kintex and Kintex Ultrascale FPGAs with fast analog, digital, and fiber optic I/O
- Implement Simulink designs using automatic VHDL code generation with HDL Coder
- To achieve fastest closed-loop rates

For closed-loop sample rates above 20kHz

100kHz and more

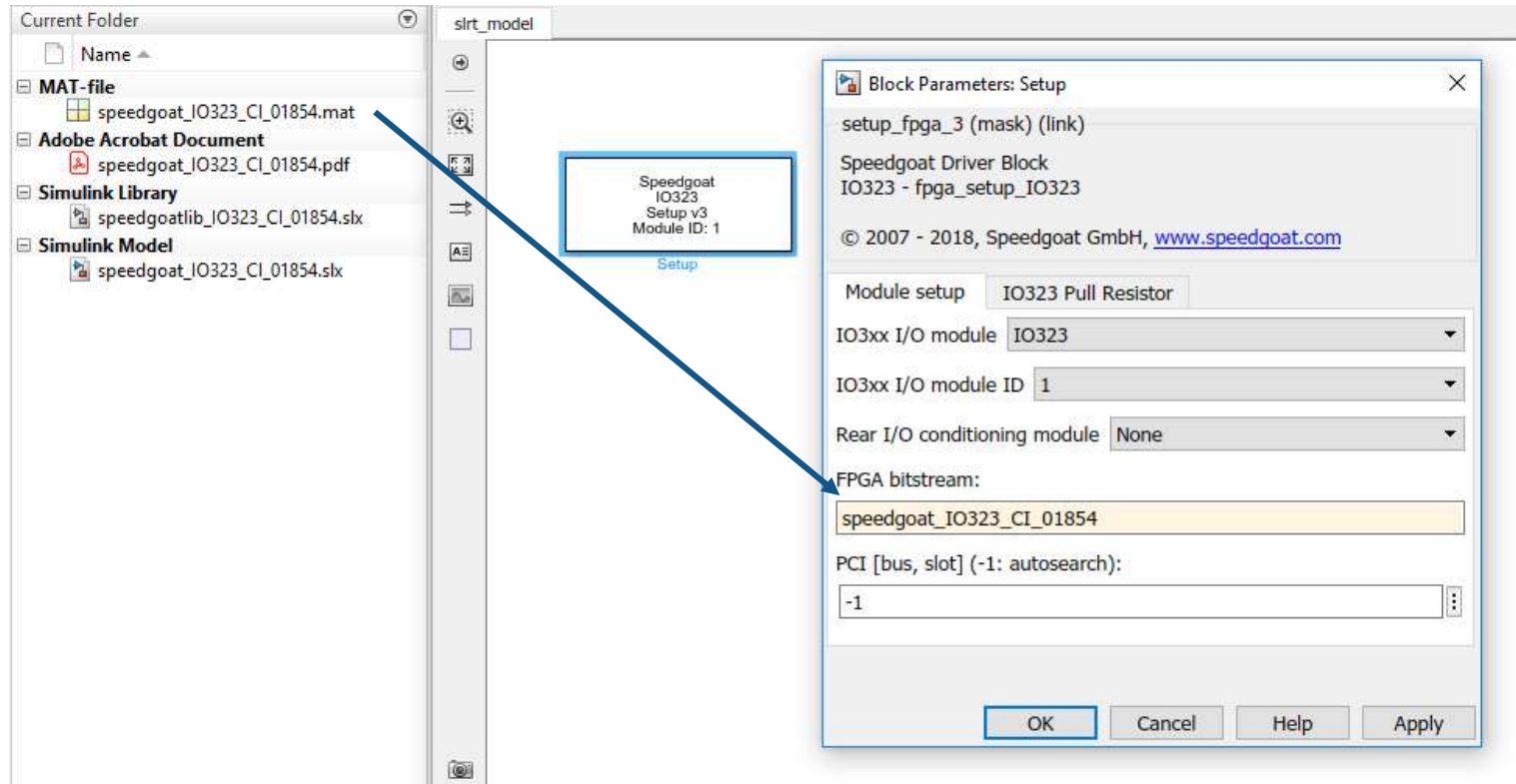


## Configurable FPGA workflow

- The FPGA-based I/O module is configured by using a bitstream file provided by Speedgoat
- The available functionality and pin mapping is defined by the FPGA bitstream
- Users may have multiple FPGA bitstreams that can be used in different models depending on their application
- The Custom Implementation package includes:
  - FPGA bitstream
  - Documentation and pin mapping
  - Test model (example)
  - Simulink library

# Configurable FPGA workflow

- Select the FPGA bitstream in the IO3xx Setup block
- The FPGA bitstream defines the pin mapping



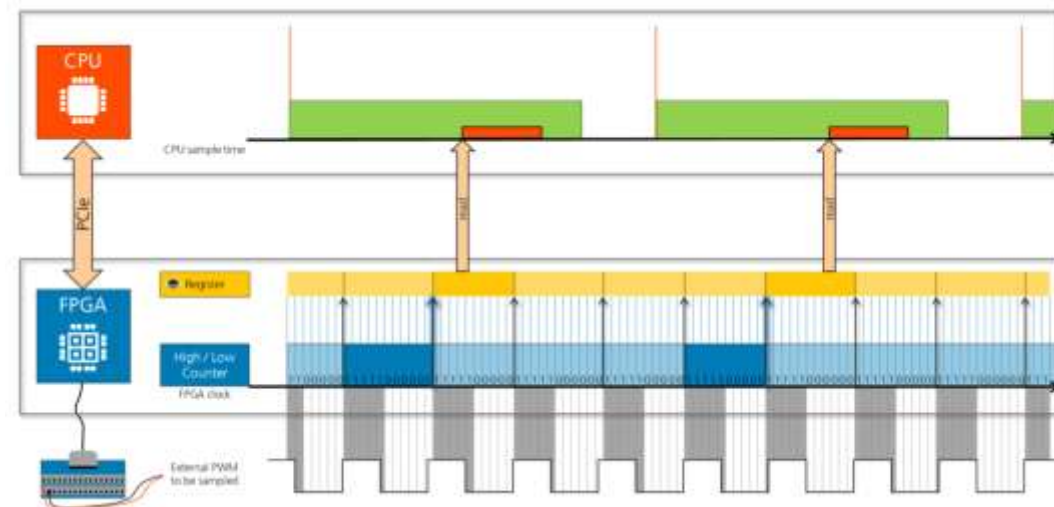
Pin	Code Module Channel	Functionality	Direction	Transceiver
1	1	PWM - A	OUT	TTL
2		PWM - B		TTL
3		PWM - Trigger		TTL
4	2	PWM - A	OUT	TTL
5		PWM - B		TTL
6		PWM - Trigger		TTL
7	3	PWM - A	OUT	TTL
8		PWM - B		TTL
9		PWM - Trigger		TTL
10	4	PWM - A	OUT	TTL
11		PWM - B		TTL
12		PWM - Trigger		TTL
13	1	CAP	IN	TTL
14		CAP -Trigger		TTL
15	2	CAP	IN	TTL
16		CAP -Trigger		TTL
17	3	CAP	IN	TTL
18		CAP -Trigger		TTL
19	4	CAP	IN	TTL
20		CAP -Trigger		TTL
21	1	SPI - CLK	IN/OUT	TTL
22		SPI - CS		TTL
23		SPI - SDO	OUT	TTL
24		SPI - SDI		TTL
25		Ground		



# Configurable FPGA workflow

## Summary

- The functionality is defined by the FPGA bitstream
- Very cost efficient HW and SW solution - New Custom Implementations can be ordered (lead time: 1-3 weeks)
- The Code Modules on the FPGA run at a faster rate and can generate or acquire signals with a higher frequency than the model sample time



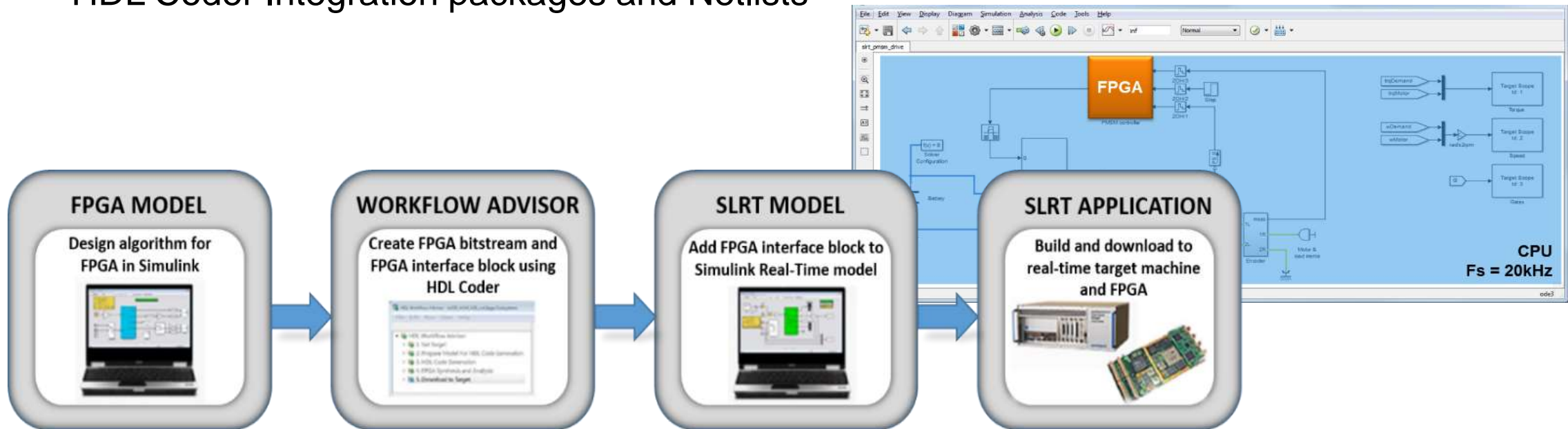
## Programmable FPGA workflow

- The FPGA-based I/O module can be programmed by the end user
- The pin mapping is defined by the end user
- Algorithms can be implemented by using HDL Coder
- The HDL Coder Integration Package provides access to the hardware resources of the I/O module, such as analog and digital I/O pins, data transfer and buffers, etc.

# Simulink Programmable FPGA I/O modules

## Run Simulink designs at fastest closed-loop rates with automated VHDL code generation

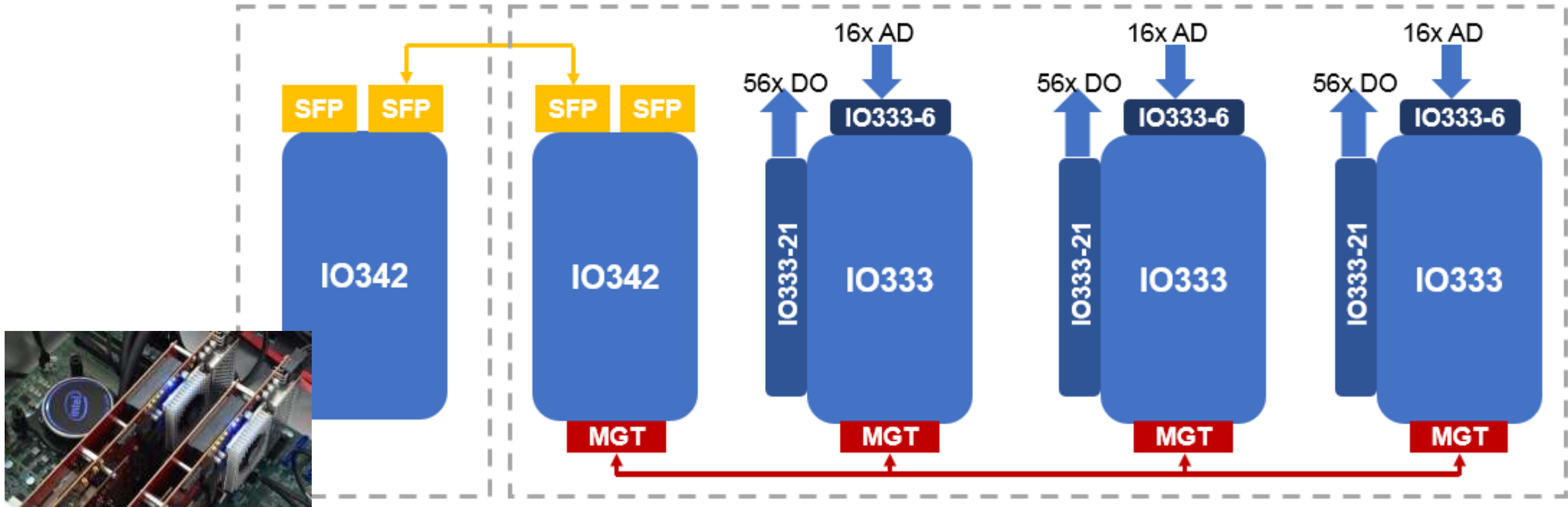
- Achieve closed-loop sample rates up to several MHz
- Immediate access to all I/O from within Simulink using HDL Coder Workflow Advisor
- Concurrently run real-time application designs in Simulink on FPGA(s) and multi-core CPU at different rates
- HDL Coder Integration packages and Netlists



# Simulink Programmable FPGA I/O modules

Interconnect many FPGA I/O modules with lowest latency link

- **Connect multiple** Flowest-latency inter-FPGA communication links and high throughput Aurora protocol using fiber optic **PGA I/O modules** with cabling
- Allows to achieve **fastest closed-loop rates** even in cases where hundres of analog and digital I/O lines, provided by multiple distributed target computers ar required

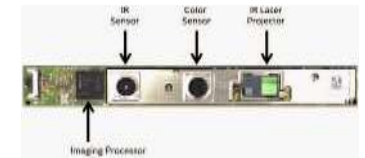
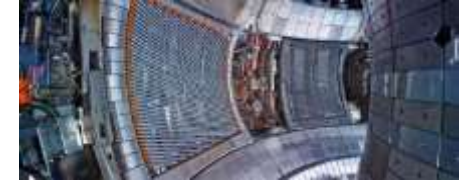




# Simulink Programmable FPGA Prototyping Application

## Examples

- **Controls: Plasma Control System for Fusion Reactor**  
32 inter-connected FPGAs with a total of 12.5 Mio logic cells, 700 analog I/O, and 74 high speed low latency fiber optic links exchanging data at 3.125 Gbps (231 Gbps aggregated)
- **Vision and Laser Controls: 3D Depth Sensing Camera for Augmented Reality**  
4 inter-connected FPGAs, fast analog I/O at 125 MHz, and digital I/O
- **Very Fast Signal Acquisition and Generation: Vision Radar Development**  
2 x inter-connected Ultrascale FPGAs, and very fast analog AD/DA at up to 5 Gbps DMA transfer support for data logging to FPGA external RAM, x86 RAM drive, and for x86/FPGA lowest-latency data exchange using interrupt free polling mode
- **Very Fast Analog Signal Acquisition: Development of New Lidar (Light Imaging, Detection, and Ranging) Technologies for Autonomous Cars**  
Ultrascale FPGA with analog I/O up to 5 Gbps

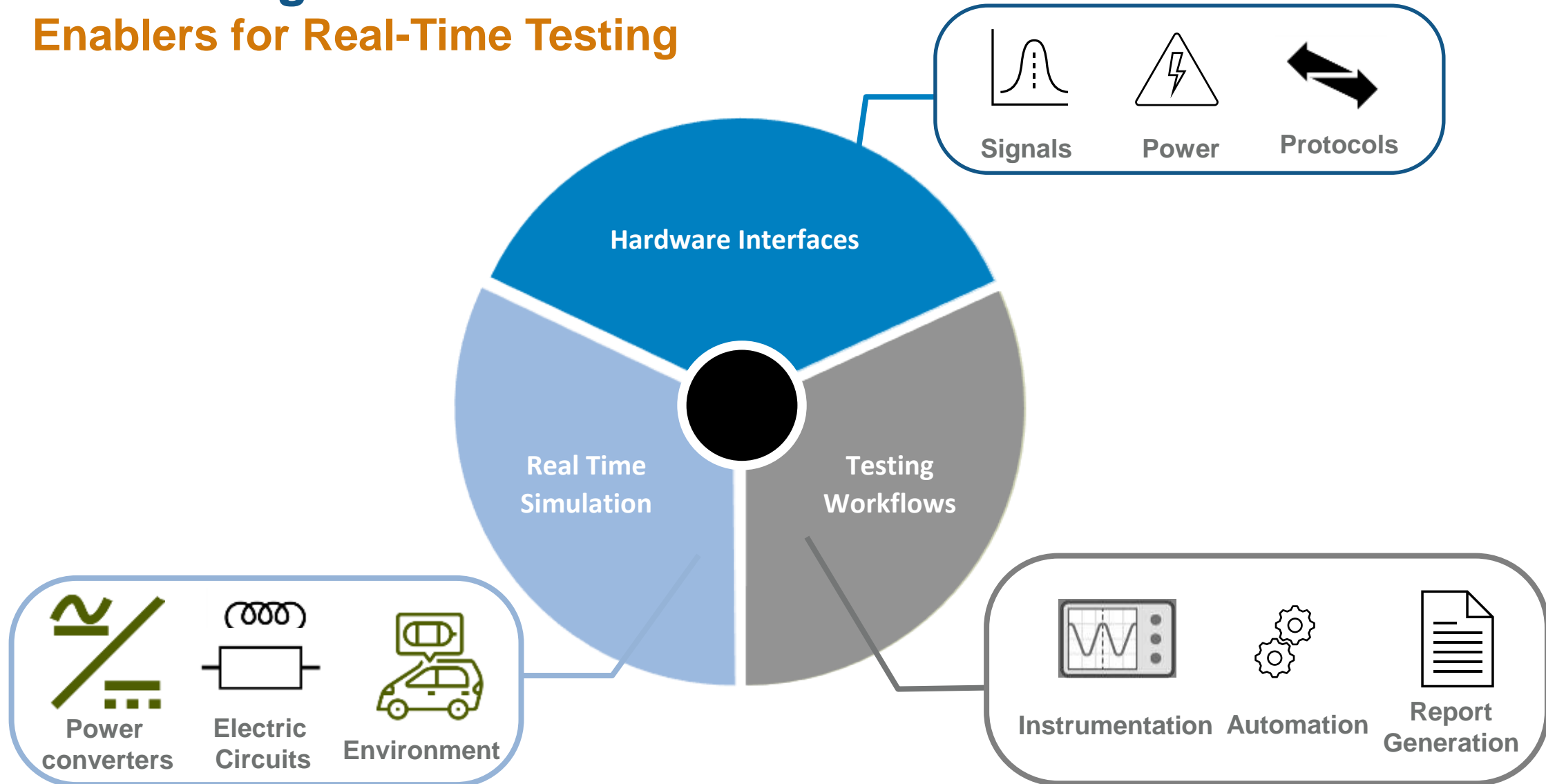


# Hardware-in-the-Loop Testing for Power Electronics



# HIL Testing of Power Electronics

## Enablers for Real-Time Testing

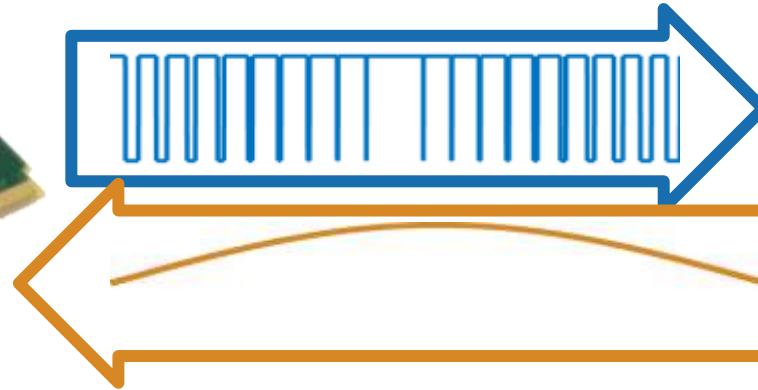


# Advantages of Hardware in the Loop (HIL) Testing

- Can replace prototypes or production hardware with a real-time system
- Easier to automate testing
- Safer than most power electronics hardware
- Start many design/test tasks earlier



**Controller**



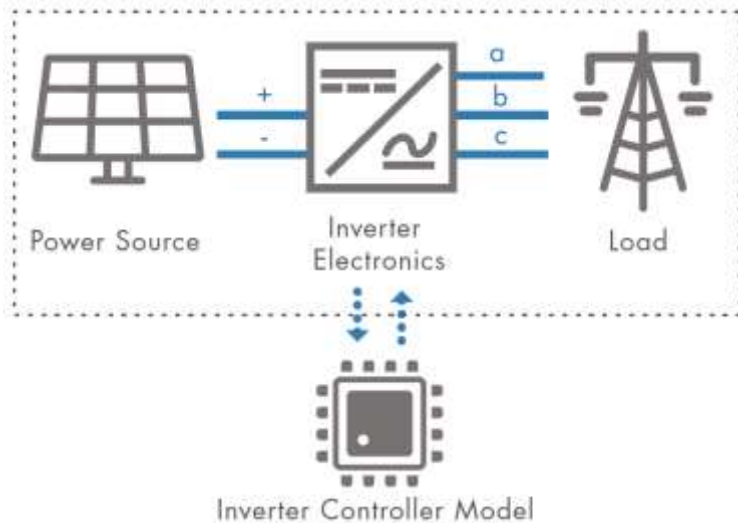
**Virtual Simulation  
(Plant)**



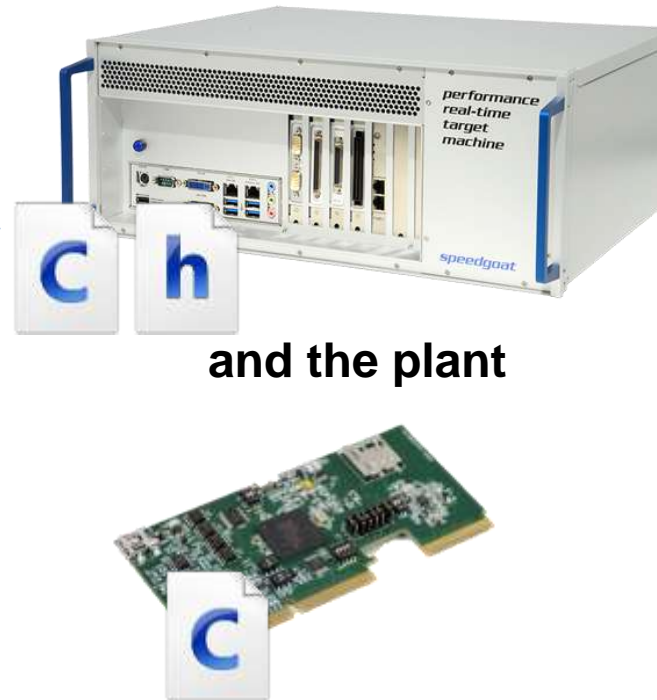
# Hardware-in-the-Loop for Power Electronics

## Workflow

**Design and optimize controls using electrical systems simulation**

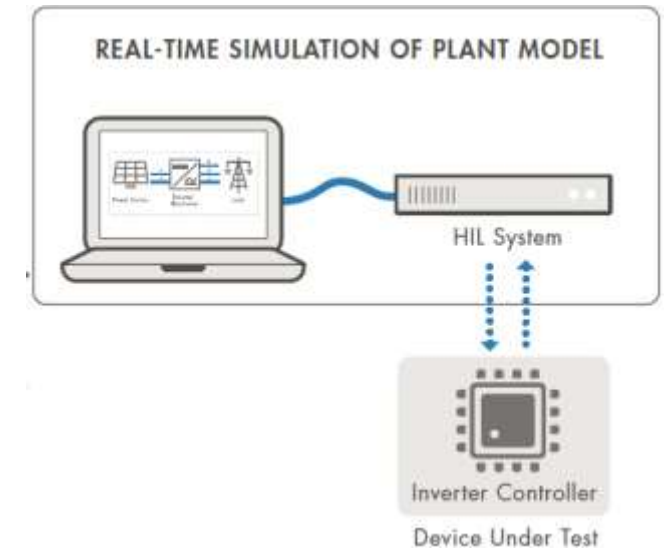


**Generate embedded code for the plant**



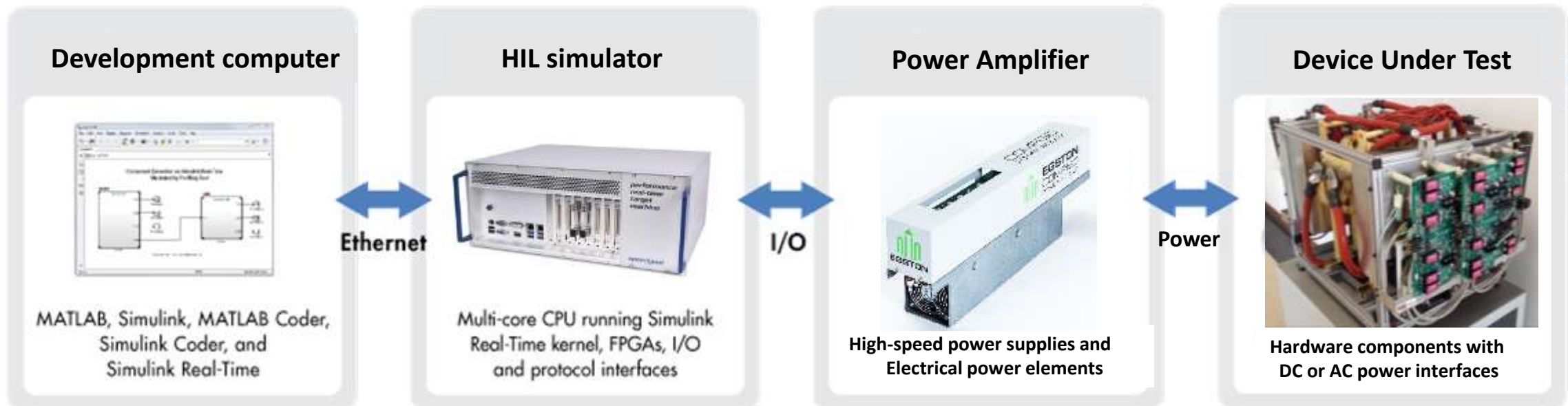
**and the plant**

**Test the control hardware using HIL simulation**



# Power HIL Solution

- Target applications like grid, battery pack, AC/DC coupling emulators
- Power amplifier from various partners (from 300 W to 2 MW)



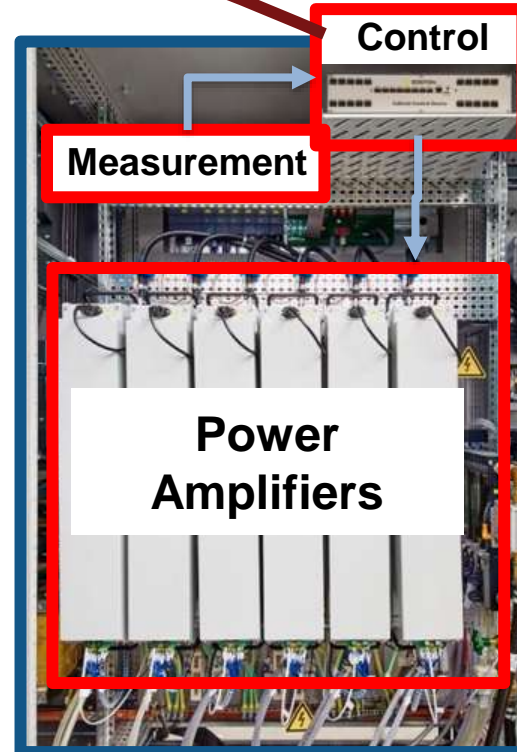
# Power HIL Test Setup Example

Speedgoat target computer



fiber optic  
4μs

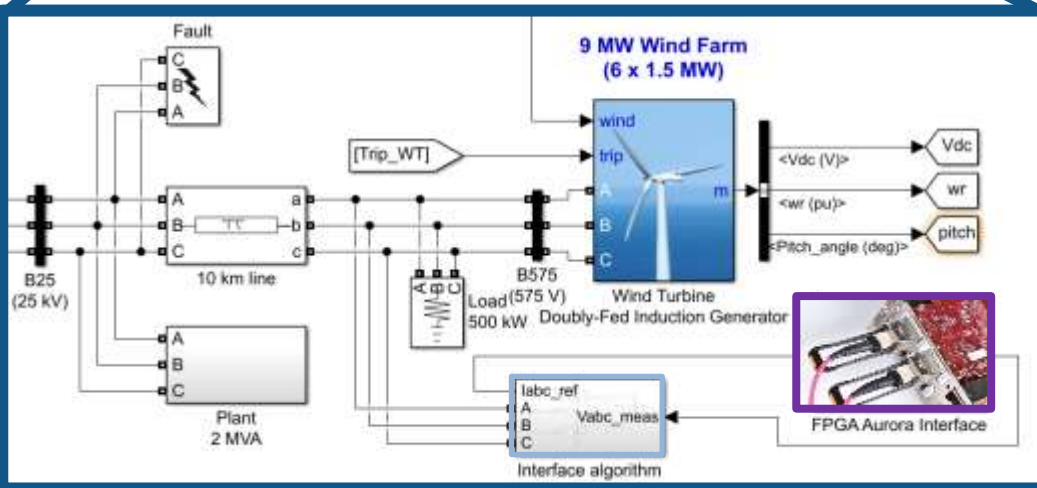
EGSTON power amplifier



Device Under Test



electric  
power



Success Story: SuperGrid Institute, France

## Rapid Controller Prototyping for Distributed DC-DC Converters

Speedgoat hardware as central and distributed controllers for highly efficient and compact DC-DC power converters

Power converter to operate at 20kHz closed-loop

Controls algorithms implemented on CPU and FPGAs, connected to DC-DC converters with analog, fiber optic, and digital pulse train I/O

Fast and agile development of next generation power distribution technology over extended ranges



“The transition from design model to real-time software was very fast thanks to the complete compatibility between MATLAB & Simulink and Speedgoat.”

Piotr Dworakowski, Supergrid



Success Story: Leonardo DRS

# FPGA-Based HIL Testing of Shipboard Power Electronics Systems

## Challenge

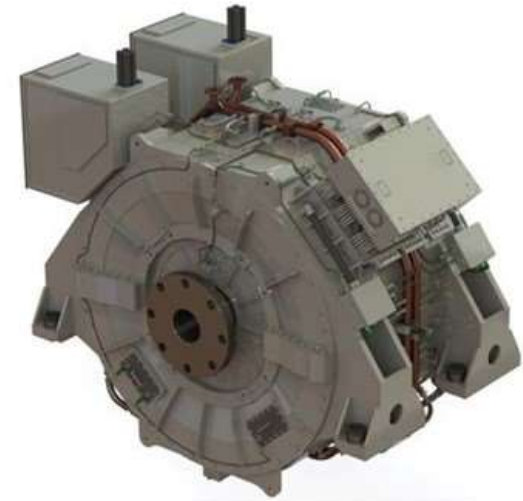
- Small-scale prototypes and hardware testbeds are simplified and do not represent the complexity of the actual hardware
- Testing time with the full-scale hardware is limited
- Not all tests are conducted with the actual hardware to avoid damaging the equipment

## Solution

- Use Simulink, Simscape, and Speedgoat products to model the plant on different levels of fidelity
- Implement hardware-in-the-loop testing, including automated fault testing

## Results

- Reduced design iteration from days to hours
- Saved cost, time, and lab space
- Reused simulation models for HIL testing



 **LEONARDO DRS**

"With Simulink, Simscape, and HDL Coder, we can develop plant models and deploy them directly to an FPGA for HIL tests; it's a no-nonsense, no-compromise way to simulate large-scale power electronics systems."

Henry Brengel,  
Leonardo DRS

## Success Story: German Aerospace Center - DLR

# Real-Time Simulation Environment for Electrical Distribution Grids

### Challenge

- Researching the robust operation of power grids that can facilitate the change to decentralized infrastructure and renewable sources of energy
- Combining of digital simulation and field testing on actual power hardware, integrating technologies from electrical, heat, and transportation (or mobility) domains
- Collaboration with groups at several other labs, both within DLR and at other institutions

### Solution

- Run simulations in real-time with Speedgoat that incorporate real-world power hardware
- Model, test and optimize control strategies and grid-in-the-loop
- Use Speedgoat FPGA I/O modules to emulate current and voltage signals from grid nodes
- Study Quarter Energy Management Systems (QEMS) by recreating the voltage at a node within a grid model
- Co-simulation environment that enables DLR to link two or more laboratories via a UDP connection

### Result

- DLR can explore scenarios that would be too costly or dangerous to test on real equipment
- Pushing processes outside their nominal operating conditions
- Efficient and effortless collaboration with other laboratories



“The testing environment lets us rapidly validate new ideas and control algorithms that we develop in house with real-time tests”

# Online Resources

Visit the Speedgoat, and the MathWorks Simulink Real-Time webpage to learn more



## Featured Applications



Rapid Control Prototyping



Hardware-in-the-Loop Simulation

